

# Game Theory and Network Systems

Summer School SIDRA 2021

## Lecture 2

### Existence of Equilibria and Potential Games

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# Outline

- ▶ Existence results for Nash equilibria
- ▶ Mixed strategies and Nash's theorem
- ▶ Potential Games

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# Strategic Form Games

- ▶  $\mathcal{V}$  finite set of **players**
- ▶  $\mathcal{A}_i$  set of **actions** of player  $i$
- ▶  $\mathcal{X} = \prod_{i \in \mathcal{V}} \mathcal{A}_i$  set of **configurations**
- ▶  $u_i : \mathcal{X} \rightarrow \mathbb{R}$  **utility function** of player  $i$
- ▶  $x \in \mathcal{X}$  **strategy profile** or **configuration**
- ▶  $x_i \in \mathcal{A}_i$  action played by player  $i$
- ▶  $x_{-i} \in \prod_{j \neq i} \mathcal{A}_j$  strategy profile of everyone but player  $i$
- ▶ utility of player  $i$  when each player  $j$  plays action  $x_j$ :

$$u_i(x_i, x_{-i}) = u_i(x)$$

- ▶  $(\mathcal{V}, \{\mathcal{A}_i\}, \{u_i\})$  is called a **(strategic form) game**

# Best Response and Nash Equilibria

- ▶ rational choice for player  $i$  given  $x_{-i}$ : **best response**

$$\mathcal{B}_i(x_{-i}) = \operatorname{argmax}_{x_i \in \mathcal{A}_i} u_i(x_i, x_{-i})$$

- ▶ A **pure strategy (P) Nash equilibrium (NE)** is  $x^* \in \mathcal{X}$  s.t.

$$x_i^* \in \mathcal{B}_i(x_{-i}^*), \quad \forall i \in \mathcal{V}.$$

- ▶ PNE  $x^* \Leftrightarrow$  no player has **strict incentive** to **unilaterally** deviate
- ▶ PNE  $x^*$  is said **strict** if  $|\mathcal{B}_i(x_{-i}^*)| = 1$  for every player  $i$
- ▶  $\mathcal{N} = \{\text{pure Nash equilibria}\}$
- ▶  $\mathcal{N}$  might be empty (e.g., discoordination, Rock-Scissor-Paper)
- ▶ PNE might not be unique (e.g., coordination, anti-coordination)

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When does a PNE exist? (And when is it unique?)

# Pure strategy Nash equilibria of continuous games

Continuous strategies: general results for existence/uniqueness

Theorem (Debreu, Glicksberg, Fan, '52)

Consider a game  $(\mathcal{V}, \{\mathcal{A}_i\}, \{u_i\})$  such that for each  $i \in \mathcal{V}$ :

- ▶  $\mathcal{A}_i \subseteq \mathbb{R}^q$  is nonempty, compact, and convex;
- ▶  $u_i(x)$  is continuous in  $x$  and concave in  $x_i$  for all  $x_{-i}$ .

Then a pure strategy Nash equilibrium exists.

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Then a pure strategy Nash equilibrium exists.

- ▶ Example: Cournot oligopoly, concave non-increasing inverse demand  $F(q)$  with  $F(\bar{q}) = 0$ , convex production costs  $c_i(x_i)$

$$u_i(x) = x_i F\left(\sum_j x_j\right) - c_i(x_i)$$



# Pure strategy Nash equilibria of continuous games

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Then a pure strategy Nash equilibrium exists.

- ▶ quasi-concavity is sufficient ;
- ▶ [Rosen'65]: sufficient conditions for uniqueness of PNE: strictly diagonally concave game;
- ▶ does not apply to finite games: e.g., Matching Penny, Rock-Scissor-Paper, ...

# Outline

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- ▶ Mixed strategies and Nash's theorem
- ▶ Potential Games

## Mixed strategies

Finite game  $(\mathcal{V}, \{\mathcal{A}_i\}, \{u_i\})$

▶ **Mixed strategy** for a player  $i$  is a probability distribution on  $\mathcal{A}_i$ :

$$z_i \in \mathcal{P}(\mathcal{A}_i)$$

▶  $z_{ia}$  = probability of choosing action  $a \in \mathcal{A}_i$

▶ action  $a \in \mathcal{A}_i \leftrightarrow$  pure strategy  $z = \delta^a$  concentrated on  $a$

▶ mixed strategy profile space:  $\mathcal{Z} = \prod_i \mathcal{P}(\mathcal{A}_i)$

▶ **multilinear utilities**: expected values assuming **independent** plays:

$$u_i(z) = \sum_x \left( \prod_j z_{jx_j} \right) u_i(x) \quad \forall z \in \mathcal{Z}, \forall i \in \mathcal{V}$$

▶ **Definition**: a **mixed strategy Nash equilibrium** is  $z^* \in \mathcal{Z}$  s.t.

$$u_i(z^*) \geq u_i(z) \quad \forall i \in \mathcal{V}, \forall z \in \mathcal{Z} \text{ s.t. } z_{-i} = z^*_{-i}$$

# Existence of mixed strategy Nash equilibria for finite games

## Theorem (Nash, 1950)

*Every finite game admits a mixed strategy Nash equilibrium.*

Proof idea:

- ▶ for every  $z \in \mathcal{Z}$  consider the best response mapping:  
 $z' = f(z)$  such that  $z'_i \in \operatorname{argmax}_{\zeta \in \mathcal{P}(\mathcal{A}_i)} u_i(\zeta, z_{-i}) \forall i \in \mathcal{V}$
- ▶ Fixed point  $z^* = f(z^*)$  is mixed strategy Nash equilibrium

Problems:

- ▶  $f$  is not well defined, there can be multiple maximum points
- ▶  $f$  may not be well-behaved and lacking a fixed point

Nash's alternative solutions:

- ▶ use **Kakutani's** fixed point theorem for **set-valued maps**
- ▶ use **Brouwer's** fixed point theorem for **continuous functions**

## Proof with Brouwer's fixed point theorem (Nash's thesis)

- ▶ For given  $z_{-i}$ ,  $u_i(z_i, z_{-i}) = \sum_{a \in \mathcal{A}_i} z_{ia} u_i(\delta^a, z_{-i})$  maximized by  $z_i$ 's supported on  $\mathcal{B}_i(z_{-i}) = \operatorname{argmax}_{a \in \mathcal{A}_i} u_i(\delta^a, z_{-i})$

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- ▶ For  $\lambda > 0$ , define  $f^\lambda : \mathcal{Z} \rightarrow \mathcal{Z}$  by

$$f_{ib}^\lambda(z) = \frac{\rho_{ib}^\lambda(z)}{\sum_{a \in \mathcal{A}_i} \rho_{ia}^\lambda(z)}$$

$$\rho_{ib}^\lambda(z) = \left[ u_i(\delta^b, z_{-i}) - \max_a u_i(\delta^a, z_{-i}) + 1/\lambda \right]_+$$

(note that  $\sum_{a \in \mathcal{A}_i} \rho_{ia}^\lambda(z) \geq 1/\lambda > 0$ )

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- ▶  $f^\lambda : \mathcal{Z} \rightarrow \mathcal{Z}$  continuous,  $\mathcal{Z}$  nonempty, compact, and convex

Brouwer's fixed point theorem  $\implies \exists z^\lambda = f^\lambda(z^\lambda) \in \mathcal{Z}$

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- ▶  $\mathcal{Z}$  compact  $\implies \exists \lambda_n \rightarrow +\infty$  such that  $z^{\lambda_n} \rightarrow z^*$



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- ▶  $\mathcal{Z}$  compact  $\implies \exists \lambda_n \rightarrow +\infty$  such that  $z^{\lambda_n} \rightarrow z^*$
- ▶  $z^*$  is mixed strategy Nash equilibrium

# Proof with Brouwer's fixed point theorem (Nash's thesis)

Last point proven by contradiction:

- ▶  $\exists i$  s.t.  $z_i^* \notin \operatorname{argmax}_{\zeta \in \mathcal{P}(\mathcal{A}_i)} u_i(\zeta, z_{-i}^*)$
- ▶  $z_{ib}^* > 0$  for some  $b \notin \operatorname{argmax}_{a \in \mathcal{A}_i} u_i(\delta^a, z_{-i}^*)$
- ▶  $u_i(\delta^b, z_{-i}^\lambda) - \max_a u_i(\delta^a, z_{-i}^\lambda) + 1/\lambda < 0$  for large  $\lambda$  (continuity)
- ▶  $\rho_{ib}^\lambda(z^\lambda) = 0$  for large  $\lambda$
- ▶  $z_b^\lambda = f(z^\lambda)_{ib} = \frac{\rho_{ib}^\lambda(z^\lambda)}{\sum_{a \in \mathcal{A}} \rho_{ia}^\lambda(z^\lambda)} = 0$  which is a contradiction.

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# Potential games

► **Definition:** A game  $(\mathcal{V}, \{\mathcal{A}_i\}, \{u_i\})$  is an (**exact**) **potential game** if there exists  $\Phi : \mathcal{A}^{\mathcal{V}} \rightarrow \mathbb{R}$  (called **potential function**) such that

$$u_i(y_i, x_{-i}) - u_i(x_i, x_{-i}) = \Phi(y_i, x_{-i}) - \Phi(x_i, x_{-i}),$$

for every  $x \in \mathcal{X}$ ,  $i \in \mathcal{V}$ , and  $y_i \in \mathcal{A}$ .

► In an **exact potential** game, for any configuration  $x$ , the **utility variation** incurred by **player  $i$**  when **changing action unilaterally** is the same as the corresponding **variation in the potential function**

## Ordinal potential games

► **Definition:** A game  $(\mathcal{V}, \{\mathcal{A}_i\}, \{u_i\})$  is an **ordinal potential game** if there exists  $\Phi : \mathcal{X} \rightarrow \mathbb{R}$  (called **ordinal potential function**) s.t.

$$u_i(y_i, x_{-i}) - u_i(x_i, x_{-i}) > 0 \iff \Phi(y_i, x_{-i}) - \Phi(x_i, x_{-i}) > 0$$

for every  $x \in \mathcal{X}$ ,  $i \in \mathcal{V}$ , and  $y_i \in \mathcal{A}_i$ .

► In an **ordinal** potential game, the **sign** of the **utility variation** incurred by player  $i$  when changing action unilaterally is the same as the **sign** of corresponding **variation in the potential** function:

$$\text{sgn}(u_i(y_i, x_{-i}) - u_i(x_i, x_{-i})) = \text{sgn}(\Phi(y_i, x_{-i}) - \Phi(x_i, x_{-i}))$$

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exact potential  $\implies$  ordinal potential  
 $\nleftarrow$

## Example: Symmetric Cournot Oligopoly

- ▶ arbitrary inverse demand (price) function  $F(q)$
- ▶ identical linear cost functions  $c_i(x_i) = cx_i$  for firms  $i = 1, \dots, n$
- ▶ profit (utility) of firm  $i$  producing  $x_i > 0$  is

$$u_i(x) = x_i F\left(\sum_j x_j\right) - cx_i$$

- ▶ this is **ordinal potential** game with potential function

$$\Phi(x) = \left(\prod_i x_i\right) \left(F\left(\sum_i x_i\right) - c\right)$$

## Example: Cournot Oligopoly with Affine Inverse Demand

- ▶ inverse demand (price) function  $F(q) = \alpha - \beta q$
- ▶ arbitrary differentiable cost functions  $c_i(x_i)$  for firms  $i = 1, \dots, n$
- ▶ profit (utility) of firm  $i$  producing  $x_i > 0$  is

$$u_i(x) = \alpha x_i - \beta x_i \sum_j x_j - c_i(x_i)$$

- ▶ this is **exact potential** game with potential function

$$\Phi(x) = \alpha \sum_i x_i - \beta \sum_i x_i^2 - \frac{\beta}{2} \sum_i \sum_{j \neq i} x_i x_j - \sum_i c_i(x_i)$$



# Potential games have Pure Strategy Nash Equilibria

**Proposition:** For an ordinal potential game, every global max point of the ord. potential function  $\Phi(x)$  is a pure Nash equilibrium, i.e.,

$$\mathcal{N} \supseteq \mathcal{N}_{max} := \operatorname{argmax}_{x \in \mathcal{X}} \Phi(x)$$

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**Proof:** Since

$$\operatorname{sgn}(u_i(y_i, x_{-i}) - u_i(x_i, x_{-i})) = \operatorname{sgn}(\Phi(y_i, x_{-i}) - \Phi(x_i, x_{-i}))$$

we have that  $x^* \in \mathcal{X}$  is a pure strategy Nash equilibrium iff

$$\Phi(y_i, x_{-i}^*) \leq \Phi(x_i^*, x_{-i}^*) \quad \forall i \in \mathcal{V}, \forall y_i \in \mathcal{A}_i$$

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► **Note:** There might be pure Nash equilibria outside  $\operatorname{argmax}_{x \in \mathcal{X}} \Phi(x)$

$\mathcal{N}$  = “local maximum points”

# Potential games have Pure Strategy Nash Equilibria

**Proposition:** For an **ordinal potential** game, every **global max point** of the ord. potential function  $\Phi(x)$  is a **pure Nash equilibrium**, i.e.,

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- ▶ **Corollary 1:** Every **finite ordinal potential** game admits (at least) a pure Nash equilibrium
- ▶ **Corollary 2:** Every **continuous ordinal potential** game with **compact** strategy space admits (at least) a pure Nash equilibrium

## Finite 2-player potential games

Every **symmetric**  $2 \times 2$  game is an exact potential game

	-	+	$\Phi$	-	+
-	a,a	d,c	-	a-c	0
+	c,d	b,b	+	0	b-d

- ▶ Coordination and anti-coordination games are potential games
- ▶ Prisoner's dilemma is a potential game
- ▶ Discoordination games and Rock-Scissor-Paper are NOT ordinal potential games, as they do not admit Nash equilibria.

# Finite Improvement Property

- ▶ length- $l$  **path**: sequence of strategy profiles  $(x^{(0)}, x^{(1)}, \dots, x^{(l)})$  such that there exist deviating players  $i_1, i_2, \dots, i_l$  with

$$x_{i_k}^{(k-1)} \neq x_{i_k}^{(k)} \quad x_{-i_k}^{(k-1)} = x_{-i_k}^{(k)} \quad \forall k = 1, \dots, l$$

- ▶ **improvement** path if deviating players have positive utility gain

$$u_{i_k}(x_{i_k}^{(k)}, x_{-i_k}^{(k)}) > u_{i_k}(x_{i_k}^{(k-1)}, x_{-i_k}^{(k)}) \quad \forall k = 1, \dots, l$$

- ▶ useful to model myopic behavior of the players
- ▶ **Finite Improvement Property (FIP)**: every improv. path is finite

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- ▶ useful to model myopic behavior of the players
- ▶ **Finite Improvement Property (FIP)**: every improv. path is finite
- ▶ **Lemma**: FIP  $\implies \exists$  pure Nash equilibrium

**Proof**: maximal path terminates in pure Nash equilibrium

# Finite Improvement Property

- ▶ Finite Improvement Property (FIP): every improv. path is finite
- ▶ Proposition: every finite ordinal potential game has the FIP



# Finite Improvement Property

- ▶ **Finite Improvement Property (FIP)**: every improv. path is finite
- ▶ **Proposition**: every **finite ordinal potential** game has the **FIP**

**Proof**: Since  $\Phi(x^{(0)}) < \Phi(x^{(1)}) < \dots < \Phi(x^{(l)})$  and  $\mathcal{X}$  finite, every improvement path can have length at most  $|\mathcal{X}| - 1$

# Finite Improvement Property

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- ▶ Converse is NOT true: e.g., the following  $2 \times 2$  game has the FIP

	-	+
-	1,0	2,0
+	2,0	0,1

but if it existed an every ordinal potential function  $\Phi$  should satisfy

$$\Phi(-, -) < \Phi(+, -) < \Phi(+, +) < \Phi(-, +) = \Phi(-, -)$$

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► Converse is NOT true

► **Definition**: Game is **generalized ordinal potential** if  $\exists \Phi : \mathcal{X} \rightarrow \mathbb{R}$

$$u_i(y_i, x_{-i}) - u_i(x_i, x_{-i}) > 0 \implies \Phi(y_i, x_{-i}) - \Phi(x_i, x_{-i}) > 0$$

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▶ **Proposition**: For **finite** games

**Generalized Ordinal Potential**  $\iff$  **Finite Improvement Property**

# Properties of Exact Potential Games

► **Lemma:** Game is exact potential  $\Leftrightarrow$  strategically equivalent to game with identical utilities:

$$u_i(x) = \Phi(x) + \psi_i(x_{-i})$$

► **Lemma:** If  $\Phi(x)$  and  $\bar{\Phi}(x)$  exact potential functions for same game, then  $\exists$  constant  $C$

$$\Phi(x) = \bar{\Phi}(x) + C \quad \forall x \in \mathcal{X}$$

► **Theorem:** Game is exact potential if and only if

$$\sum_{i=1}^4 u_{i_k}(x^{(k)}) - u_{i_k}(x^{(k-1)}) = 0$$

for every length-4 closed path  $(x^{(0)}, x^{(1)}, x^{(2)}, x^{(3)}, x^{(4)} = x^{(0)})$

null “cirquitation” on 4-cycles

## Finite 2-player potential games

► **Proposition:** Symmetric two player game with utilities

$$u_1(a, b) = U_{ab} \quad u_2(a, b) = U_{ba}$$

is exact potential if and only if

$$U = S + C$$

where  $S$  symmetric and  $C$  constant on columns

## Smooth potential games

- **Proposition:** Game  $(\mathcal{V}, \{\mathcal{A}_i\}, \{u_i\})$ ,  $\mathcal{A}_i \subseteq \mathbb{R}$  interval,  $u_i \in \mathcal{C}^2$ .  
Then, the game is an exact potential if and only if

$$\frac{\partial^2}{\partial x_i \partial x_j} u_i(x) = \frac{\partial^2}{\partial x_j \partial x_i} u_j(x)$$

for every  $i, j \in \mathcal{V}$  and  $x \in \mathcal{X}$ . Moreover, in this case a potential function is

$$\Phi(x) = \sum_i \int_{\Gamma_{\bar{x} \rightarrow x}} \frac{\partial u_i}{\partial x_i}(s) \cdot ds$$

## Congestion games

For player set  $\mathcal{V}$ , action set  $\mathcal{A}$  and  $c_a : \mathbb{Z}_+ \rightarrow \mathbb{R}$  for  $a \in \mathcal{A}$ .

$$x \in \mathcal{X}, a \in \mathcal{A} \quad n_a^x = |\{i \in \mathcal{V} \mid x_i = a\}|$$

Utility of unit  $i$ :  $u_i(x) = -c_{x_i}(n_{x_i}^x)$ .

The game  $(\mathcal{V}, \mathcal{A}, \{u_i\})$  is called a **congestion** game.

- ▶ utility of a player only depends on total number of players playing the same action.
- ▶ Actions  $\leftrightarrow$  shared resources. If  $c_a$ 's are non-decreasing, the more units use the same resource, the worse the performance.



## Congestion games (cont'd)

An important extension:

- ▶ set of resources  $\mathcal{E}$  (e.g., links in a transportation network) and, for  $e \in \mathcal{E}$ , congestion costs  $c_e : \mathbb{Z}_+ \rightarrow \mathbb{R}_+$ ,
- ▶ action set  $\mathcal{A} \subseteq 2^{\mathcal{E}}$  consists of a family of subsets of  $\mathcal{E}$ .

$$x \in \mathcal{A}^{\mathcal{V}}, e \in \mathcal{E} \quad n_e^x = |\{i \in \mathcal{V} \mid e \in x_i\}|$$

- ▶  $x \in \mathcal{A}^{\mathcal{V}}, u_i(x) = - \sum_{e \in x_i} c_e(n_e^x)$ .

# Congestion games are exact potential games

## Theorem

$\Phi(x) = - \sum_{e \in \mathcal{E}} \sum_{h=1}^{n_e^x} c_e(h)$  is a potential

**Proof:** Let  $y, x \in \mathcal{A}^V$  be such that  $y_j = x_j$  for every  $j \neq i$ .

$$\begin{aligned}\Phi(y) - \Phi(x) &= - \sum_{e \in \mathcal{E}} \left[ \sum_{h=1}^{n_e^y} c_e(h) - \sum_{h=1}^{n_e^x} c_e(h) \right] \\ &= - \sum_{e \in y_i \setminus x_i} \left[ \sum_{h=1}^{n_e^y} c_e(h) - \sum_{h=1}^{n_e^y - 1} c_e(h) \right] \\ &\quad - \sum_{e \in x_i \setminus y_i} \left[ \sum_{h=1}^{n_e^x - 1} c_e(h) - \sum_{h=1}^{n_e^x} c_e(h) \right] \\ &= - \sum_{e \in y_i \setminus x_i} c_e(n_e^y) + \sum_{e \in x_i \setminus y_i} c_e(n_e^x) \\ &= - \sum_{e \in y_i} c_e(n_e^y) + \sum_{e \in x_i} c_e(n_e^x) \\ &= u_i(y) - u_i(x)\end{aligned}$$